

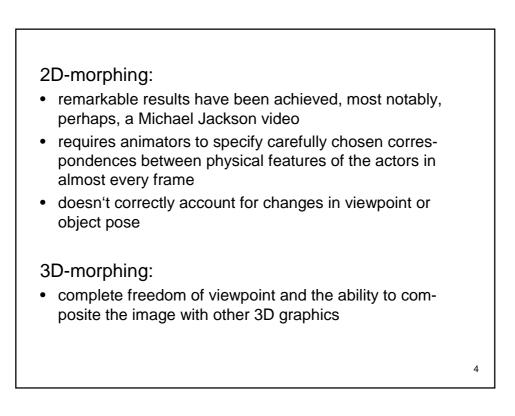
Motivation

Factors that make realistic facial animation elusive:

- face is an extremely complex geometric form
- face exhibits countless tiny creases and wrinkles, as well as subtle variations in color and texture that are crucial for comprehension of expressions

Even more problematic to animate:

- facial movement is a product of the underlying skeletal and muscular forms
- we have an uncanny ability to read expressions and detect the slightest deviation



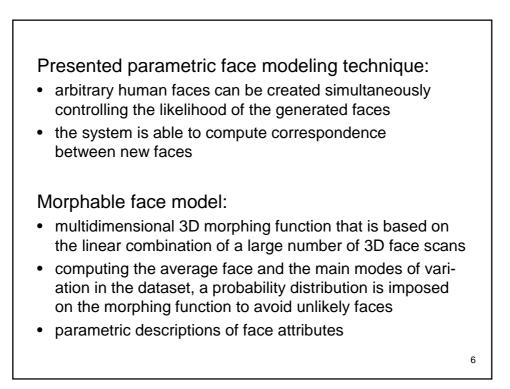
Introduction

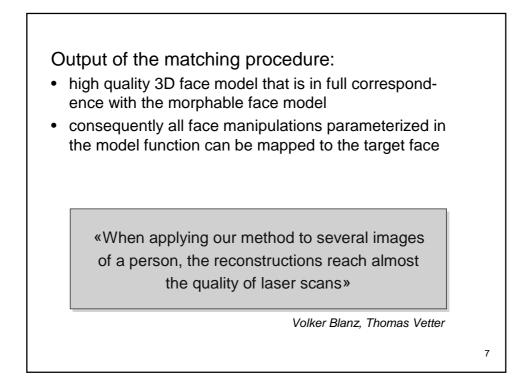
Problem of finding corresponding feature locations:

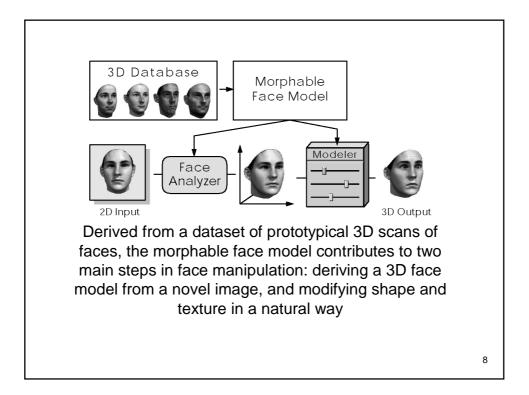
- a limited number of labeled feature points marked in one face (50..300) must be located precisely in another face
- only a correct alignment of all these points allows acceptable intermediate morphs
- automated matching techniques only for very prominent feature points

Problem of separating realistic faces

• requires time-consuming manual work combined with the skills of an artist

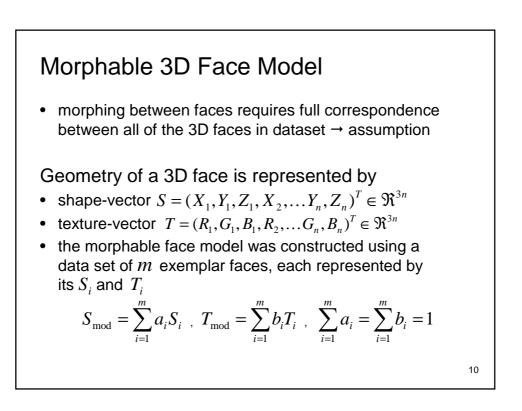


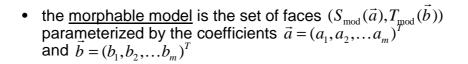






- laser scans (*Cyberware*[™]) of 200 heads of young adults (100 male and 100 female, Caucasian) were used
- head structure data in a cylindrical representation: radii r(h,φ) of surface points, sampled at 512 equallyspaced angles φ and vertical steps h, and RGB-color values R(h,φ), G(h,φ), B(h,φ)
- all faces were without makeup, accessories, and facial hair
- the subjects were scanned wearing bathing caps, that were removed digitally
- vertical cut behind the ears, horizontal cut to remove the shoulders



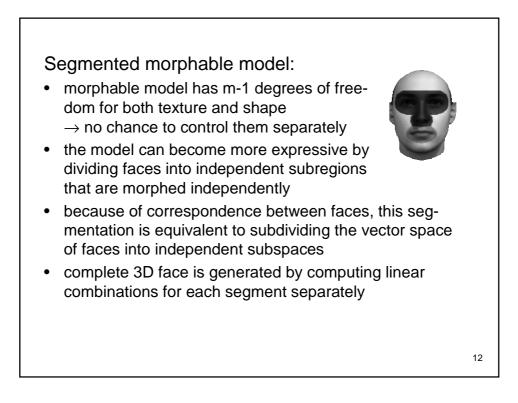


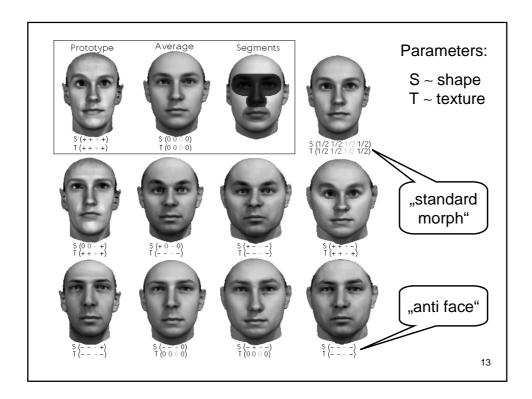
 arbitrary new faces can be generated by varying the parameters that control shape and texture

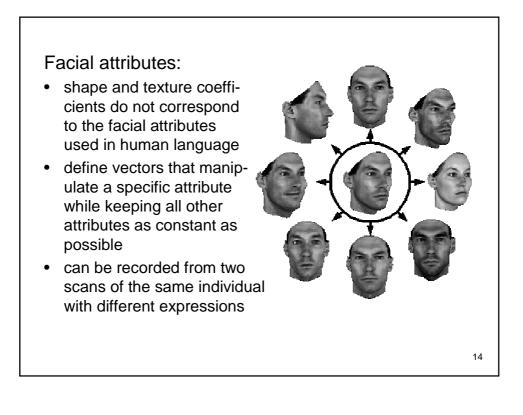
Probability distribution:

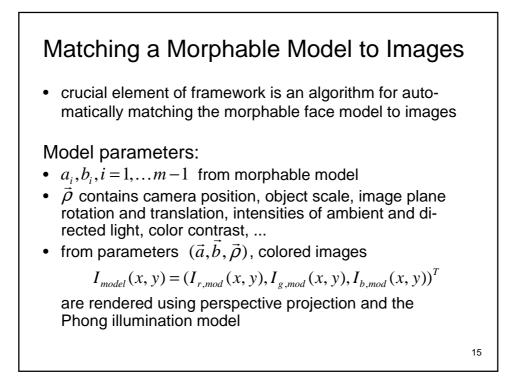
- distribution for the coefficients a_i and b_i estimated from example set of 200 faces in order to quantify the results in terms of their plausibility of being faces
- \rightarrow control of the likelihood of the appearance of the generated faces











the reconstructed image is supposed to be closest to the input image in terms of Euclidean distance
E_I = ∑_{x,y} ||I_{input}(x, y) - I_{model}(x, y)||²

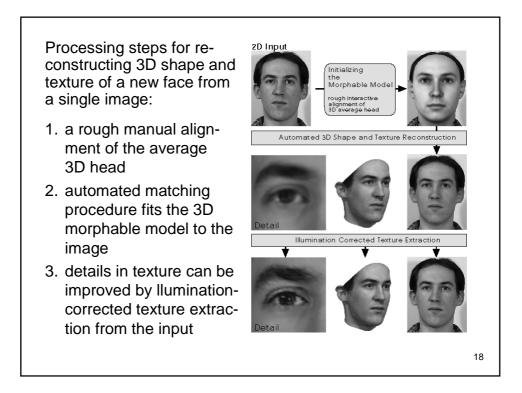
along with the desired solution, many non-face-like surfaces lead to the same image → shape and texture vectors in morphable model are restricted to the vector space spanned by the database

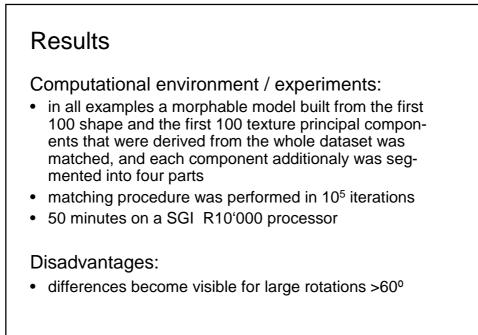
Algorithm (coarse to fine):

- the first set of iterations is performed on a downsampled version of the input image with a low resolution morphable model
- start by optimizing only the first coefficients a_i and b_i controlling the first principal components, along with all parameters ρ_i
- in subsequent iterations, more and more principal components are added
- in the last iterations, the face model is broken down into segments. With parameters ρ_i fixed, coefficients a_i and b_i are optimized independently for each segment

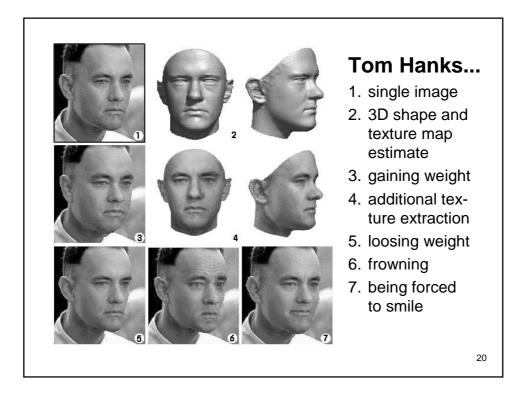
Variation: multiple input images \rightarrow fixes e.g. occluded areas

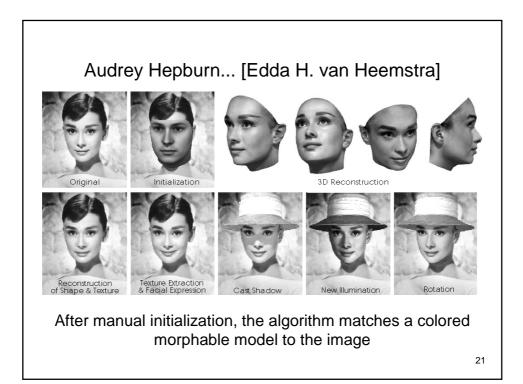
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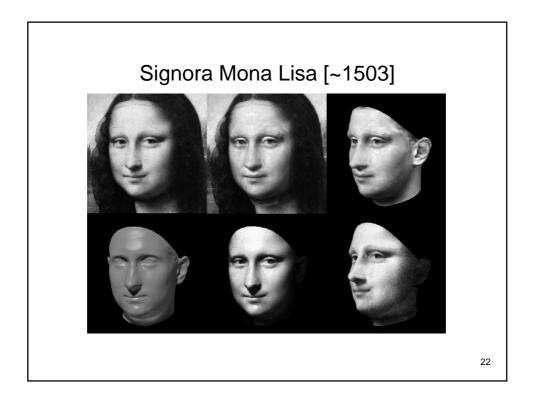


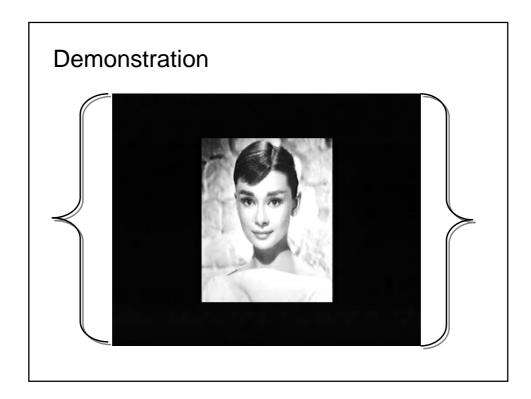


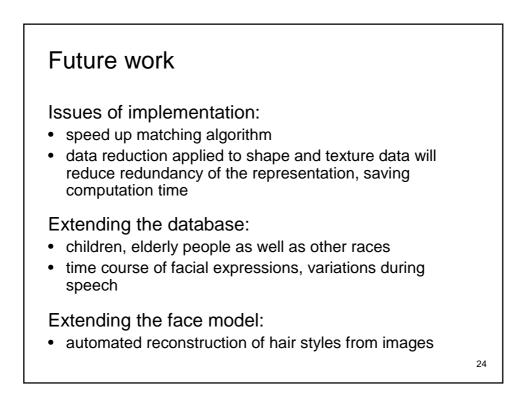














Advantages:

- easy idea, many features
- split of the image into face and background
- · combination of face with other 3D graphic objects

Many applications:

• movies, 3D-visualization on the web, forgery...

Possible extensions:

• not only faces, but whole bodies

