

PHYSICALLY-BASED SIMULATION OF SOFT BODIES IN INTERACTIVE SYSTEMS AND GAMES

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Project Introduction

- Interactive Game with Physically-based Interactive System
- Interactive System consists of Soft-Bodies & Rigid-Bodies
- □ Implementation of Forces applied on Soft-Bodies & Rigid-Bodies

Simulation Methods

- Verlet Integration [Advanced Character Physics T.J.]
- Rigid Body Simulation using Particles
- Collision Detection & Handling
- Soft-Body Simulation

MILESTONES – What we achieved

Project Goals

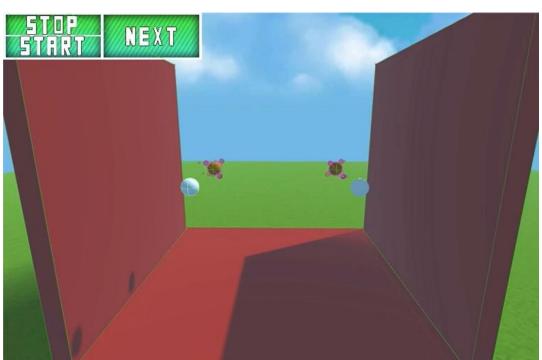
- 1. Set up Basic Scene
- Rigid-Body Implementation
- Collision Handling for Rigid-Body
 - OBB vs OBB (90%)
 - OBB vs Sphere 🗸
 - Sphere vs Sphere
- Soft-Body Implementation
- Soft-Body Collision Handling
- Interactivity

"Above and Beyond!": Additional Goals

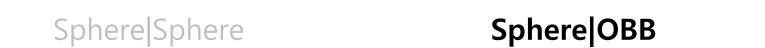
- Cloth Simulator
 - Tool with parameter settings Collisions with Spheres/Obb
- Dynamic Octree (90%)
- Soft-Bodies of rigged and skinned meshes

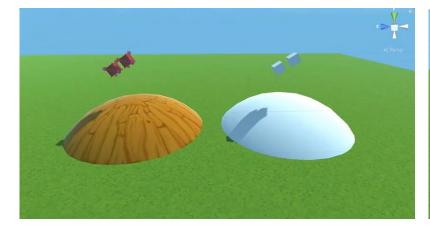
Sphere|Spher e

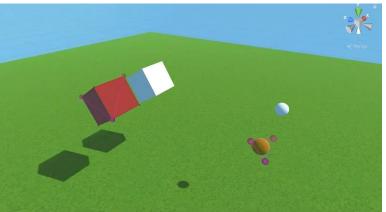
Sphere|OBB

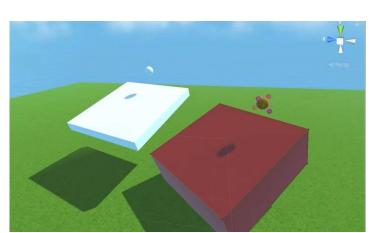


OBB|OBB



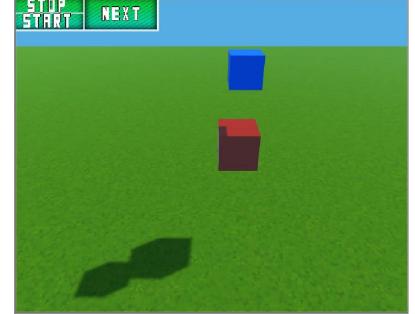


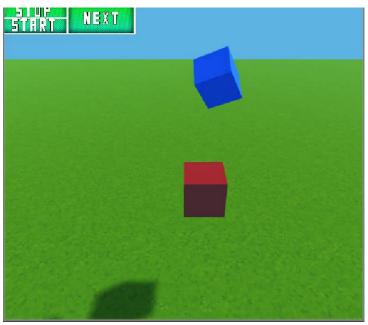


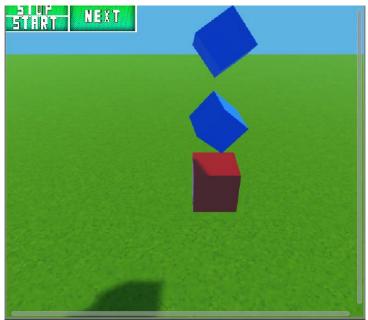


OBB|OBB

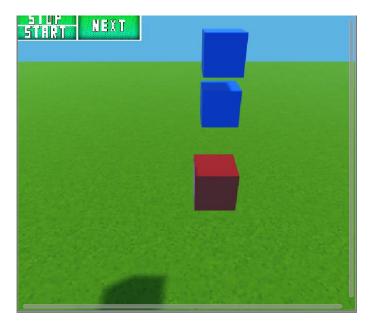




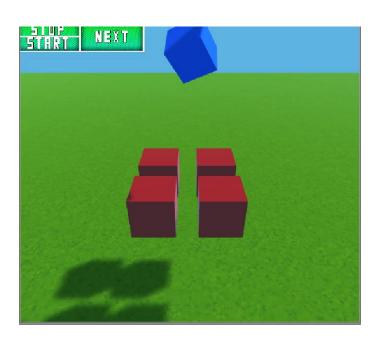






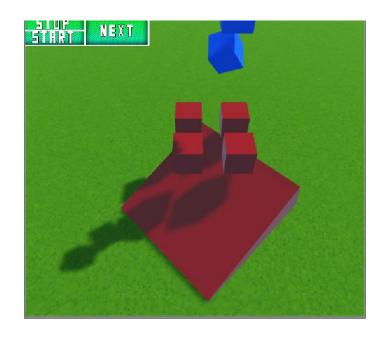


Sphere OBB

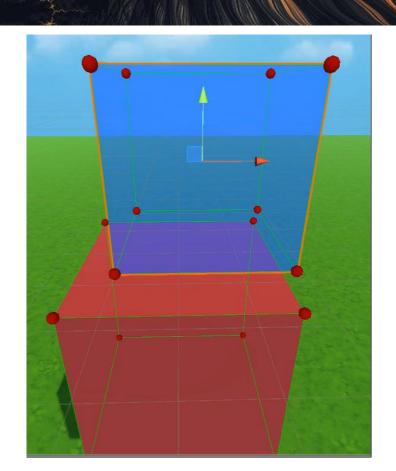


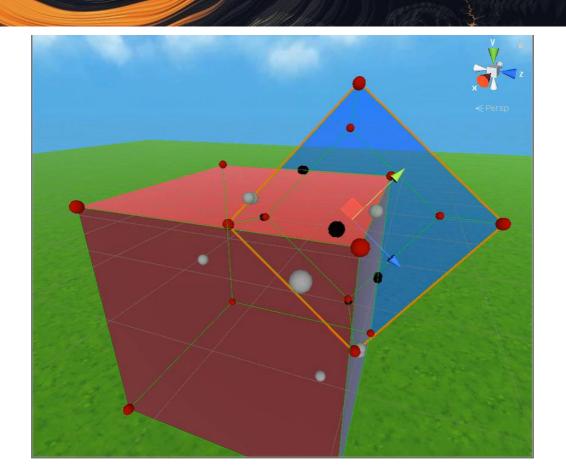
OBB|OBB 🔔



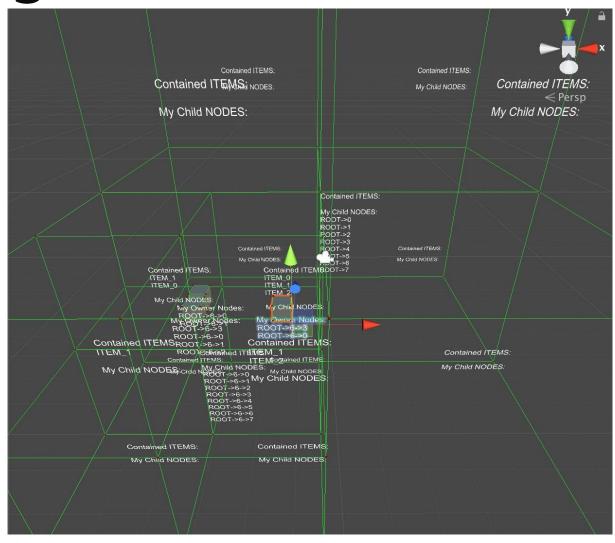


Challenges – OBB|OBB Collision



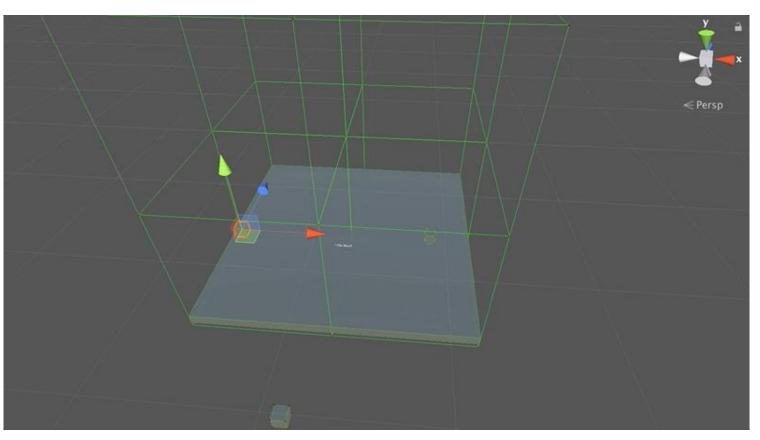


Challenges - Octree



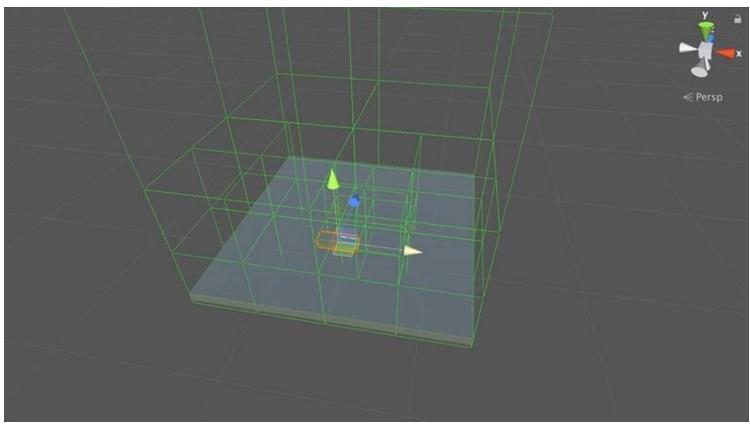
Challenges - Octree

Octree for collision detection

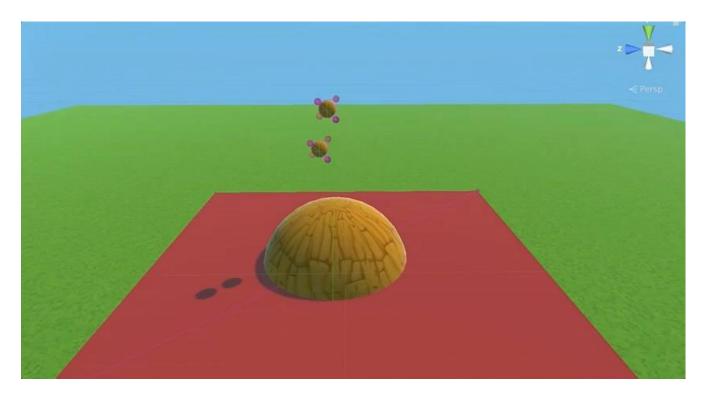


Challenges - Octree

Octree for collision detection

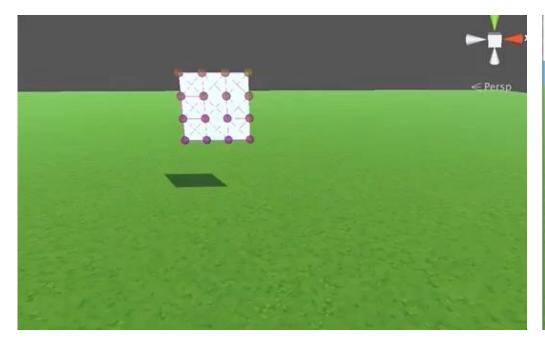


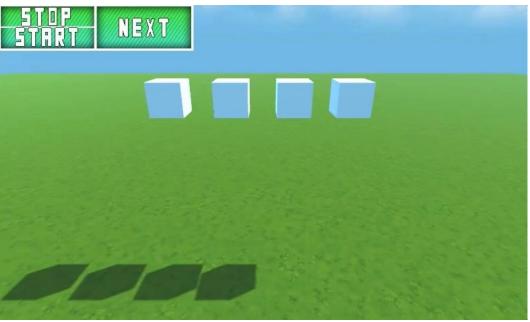




Soft Body

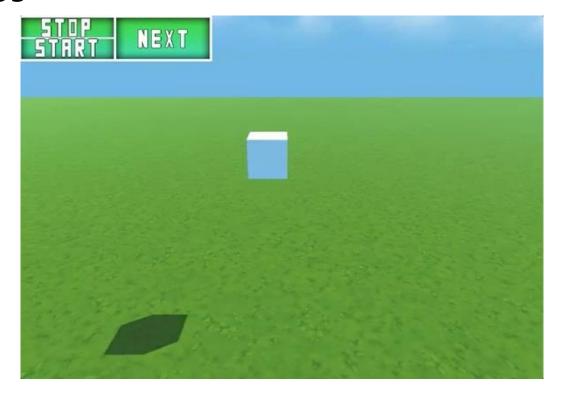
Constraint solver using mesh



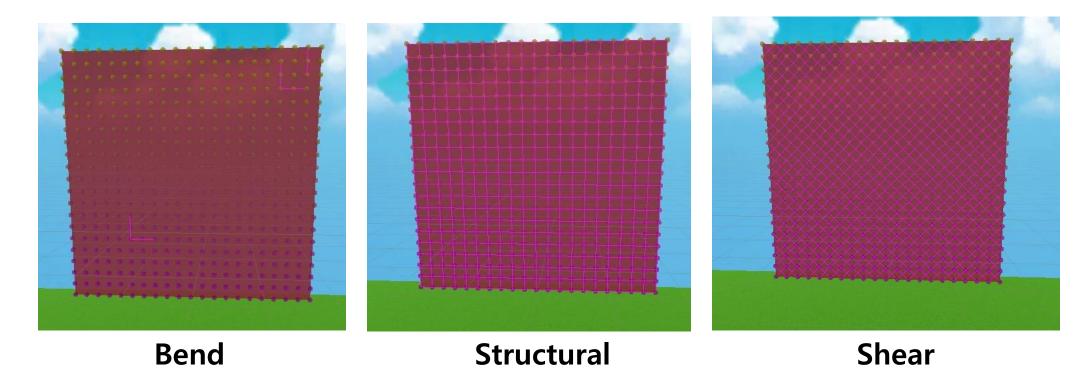


Soft Body

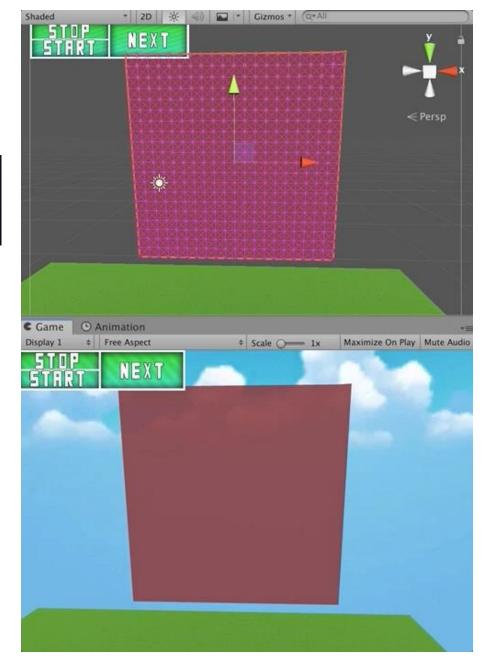




Composition/Construction





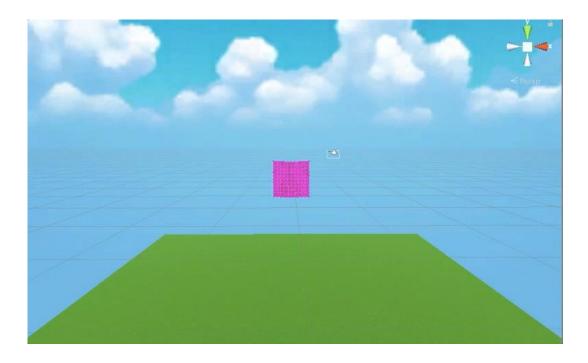


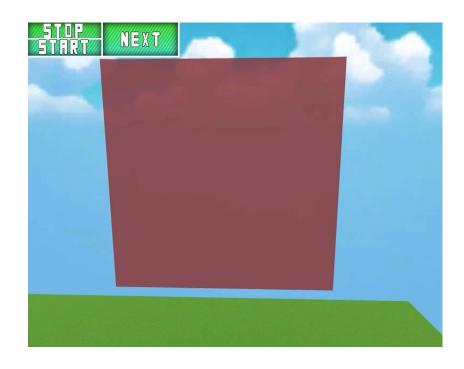


Collisions

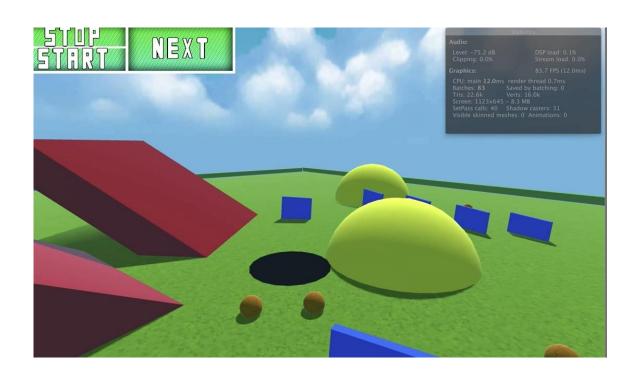








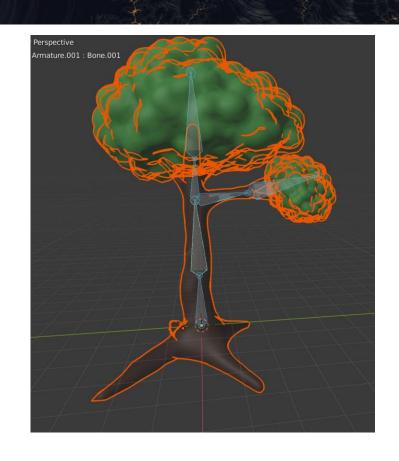
Interactivity



Softbodies of skinned meshes

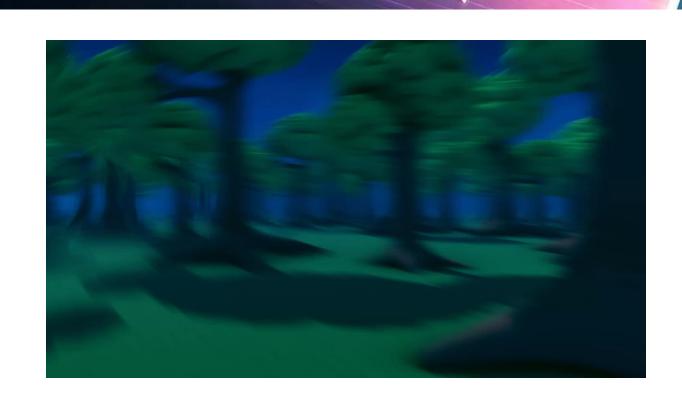


Softbodies of skinned meshes





The Return of the Meatballs



THANKS!

