

**T4 –
(Non-)linear Diffusion**

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Diffusion – Basics

- Idea: Use theory from physics/chemistry for image processing.
- Diffusion: balancing of heat, chemical concentrations, fluids, material, ...
... and intensities in a picture
- As last exercise: we still search for (reconstruction) filters

Diffusion – Notation

- Gradient:
 - scalar function
 - „slope“
$$\nabla u(x, y) = \begin{pmatrix} \frac{\partial}{\partial x} u(x, y) \\ \frac{\partial}{\partial y} u(x, y) \end{pmatrix}$$
- Divergence:
 - vector field
 - „transpiration“ *material leaving a infinitely small volume*
$$\nabla \cdot j = \text{div} j = \left(\frac{\partial}{\partial x} j_x, \frac{\partial}{\partial y} j_y \right)$$
- Laplace operator:

$$\nabla^2 = \nabla \cdot \nabla = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right)$$

Diffusion – Laws

- Fick's law:** concentration differences in u cause a flux j (vector field) compensating for the difference

$$j = -D \cdot \nabla u$$
material dependent diffusivity
- Continuity equation:** changes in u over time can only be caused by moving material

$$\frac{\partial}{\partial t} u = -\nabla \cdot j$$

$$\nabla \cdot j = \lim_{V \rightarrow 0} \frac{\int_S j \cdot da}{V}$$

Diffusion – Diffusion Equation

- relates temporal changes of u to the flux caused by u
- i.e. relates time and space

$$\frac{\partial}{\partial t} u = \text{div}(D \nabla u) = \nabla \cdot (D \nabla u)$$

- Image processing: „material“ is intensity => D can depend on image structure

Diffusion – Diffusivity Defines Type

- Homogeneous diffusion: D does not depend on space
 - Ex: constant scalar diffusion *Aufgabe 1*
- Inhomogeneous diffusion: D is space dependent *Aufgabe 2*
- Nonlinear diffusion: D depends on u
- Isotropic diffusion: $\nabla u \parallel j$
 - can be time and/or space dependent
 - Ex: scalar diffusion is linear isotropic

Aufgabe 1

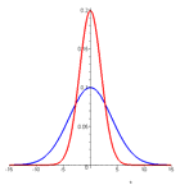
- isotropic: $D = 1$

$$\frac{\partial}{\partial t} u = \nabla \cdot (D \nabla u) = \nabla^2 u = \frac{\partial^2}{\partial x^2} u + \frac{\partial^2}{\partial y^2} u$$

$D = 1$ Laplacian

Aufgabe 1 a)

- diffused δ is Gaussian
- δ can be defined as a Gaussian:



$$\delta(x) = \lim_{\sigma \rightarrow 0} \text{Gauss}(x, \sigma)$$

Aufgabe 1 b), c), d)

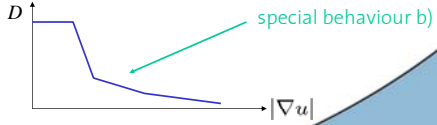
- Numerically solve diffusion process:
 - Discretization
- b) Taylor expansion: $u(t + \tau) \approx u(t) + \tau \frac{\partial}{\partial t} u(t) + \dots$

higher order terms dropped

 - Solve for derivative
 - Second derivative: recursive
 - „central differences“: lecture slides/google
- c) plug in...
- d) analyze result from c)

Aufgabe 2

- Problem: linear isotropic diffusion blurs edges
- Solution: decrease the diffusion close to edges
 - Gradient is large at edges (see Laplacian of Gaussian in last exercise sheet)
 - Model D inverse proportional to $|\nabla u|$
- a): draw the desired behaviour in 1D



Aufgabe 2 b), c), d)

- Perona-Malik: special definition of D inverse proportional to $|\nabla u|$

$$D(|\nabla u|) = \frac{1}{1 + |\nabla u|^2 / \lambda^2}$$

- b) 1D: divergence is simple derivative => substitute, solve.
- c) „step edge“: non-ideal edge
- d) interpret, consult lecture slides

Aufgabe 3

- Yet another definition for $D(|\nabla u|)$
- Matlab commands: solution last exercise
- a) self – explaining demos
- b) – d), f):
 - look at the jpg-image either as the faulty image – reconstruction
 - Simply treat diffusion as another filter
- e): actual reconstruction



Aufgabe 3

- b) cf. Aufgabe 1 a)
- c) λ „edge smooting and edge enhancement“
- d) keep λ fixed but increase time
- e): reconstruction
 - That's the actual idea of diffusion
 - Hint: will not result in the jpg-image
- f): cf. Aufgabe 1 d)